

HW7.2 3, 4, 5, 6

$K=?$ so that

$Q = 0.00833$ going thru each branch

12.5 $L_1 = L_2 = 30\text{m}$ $\gamma = 9.81 \text{ kN/m}^3$ $\nu = 1.3 \times 10^{-6} \text{ m}^2/\text{s}$

$D_1 = D_4 = 149 \text{ mm} = 0.149 \text{ m}$

$D_2 = 93 \text{ mm} = 0.093 \text{ m}$

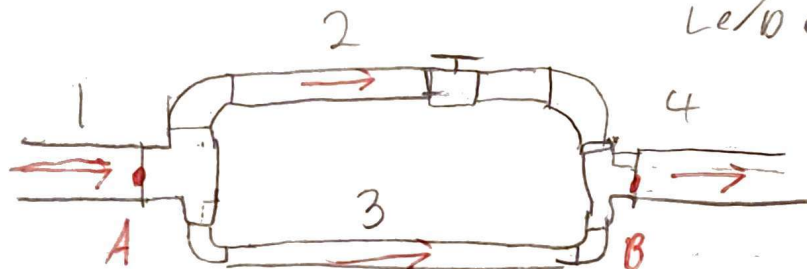
$D_3 = 47 \text{ mm} = 0.047 \text{ m}$

$Q = 500 \text{ L/min}$ in each branch

$= 0.00833 \text{ m}^3/\text{s}$

$L_e/D \text{ tee} = 60$

$L_e/D \text{ elbow} = 30$



$$\frac{P_A}{\gamma} + \frac{V_A^2}{2g} + z_A = \frac{P_B}{\gamma} + \frac{V_B^2}{2g} + z_B + h_{LAB} \rightarrow \frac{\Delta P}{\gamma} = h_{LAB}$$

$$\frac{\Delta P}{\gamma} = h_{LAB2}$$

$$\frac{\Delta P}{\gamma} = h_{LAB3}$$

Path 2 losses

Major: pipe 2

Minor: 2 tees, reduction, valve, 2 elbows, enlargement

Path 3 losses

Major: pipe 3

Minor: 2 tees, reduction, 2 elbows, enlargement.

Path 2

$$\frac{\Delta P}{\gamma} = f_2 \frac{L_2}{D_2} \frac{V_2^2}{2g} + 2f_1 \left(\frac{L_e}{D} \right)_{\text{tee}} \frac{V_1^2}{2g} + K_{\text{red}} \frac{V_2^2}{2g} + K_{\text{valve}} \frac{V_2^2}{2g} + 2f_2 \left(\frac{L_e}{D} \right)_{\text{elbow}} \frac{V_2^2}{2g} + K_{\text{enl}} \frac{V_2^2}{2g}$$

$$= f_2 \frac{L_2}{D_2} \frac{16Q_2^2}{\pi^2 D_2^4 2g} + 2f_1 \left(\frac{L_e}{D} \right)_{\text{tee}} \frac{16Q_1^2}{\pi^2 D_1^4 2g} + K_{\text{red}} \frac{16Q_2^2}{\pi^2 D_2^4 2g} + K_{\text{valve}} \frac{16Q_2^2}{\pi^2 D_2^4 2g} + 2f_2 \left(\frac{L_e}{D} \right)_{\text{elbow}} \frac{16Q_2^2}{\pi^2 D_2^4 2g} + K_{\text{enl}} \frac{16Q_2^2}{\pi^2 D_2^4 2g}$$

$$\frac{\Delta P}{\gamma} = f_2 \frac{L_2}{D_2} \frac{8Q_2^2}{\pi^2 D_2^4 g} + 2f_1 \left(\frac{L_e}{D}\right)_{tee} \frac{8Q_1^2}{\pi^2 D_1^4 g} + K_{red} \frac{8Q_2^2}{\pi^2 D_2^4 g} + K_{valve} \frac{8Q_2^2}{\pi^2 D_2^4 g} + 2f_2 \left(\frac{L_e}{D}\right)_{el} \frac{8Q_2^2}{\pi^2 D_2^4 g} + K_{enl} \frac{8Q_2^2}{\pi^2 D_2^4 g}$$

$$\frac{\Delta P}{\gamma} = f_2 \frac{8Q_2^2}{\pi^2 D_2^4 g} \left(\frac{L_2}{D_2} + 2 \left(\frac{L_e}{D}\right)_{elbow} \right) + \frac{8Q_2^2}{\pi^2 D_2^4 g} (K_{red} + K_{valve} + K_{enl}) + 2f_1 \left(\frac{L_e}{D}\right)_{tee} \frac{8Q_1^2}{\pi^2 D_1^4 g}$$

Path 3

$$\frac{\Delta P}{\gamma} = f_3 \frac{8Q_3^2}{\pi^2 D_3^4 g} \left(\frac{L_3}{D_3} + 2 \left(\frac{L_e}{D}\right)_{elbow} \right) + \frac{8Q_3^2}{\pi^2 D_3^4 g} (K_{red} + K_{enl}) + 2f_1 \left(\frac{L_e}{D}\right)_{tee} \frac{8Q_1^2}{\pi^2 D_1^4 g}$$

$$Q_1 = Q_4 = Q_2 + Q_3 = 0.00833 \text{ m}^3/\text{s} + 0.00833 \text{ m}^3/\text{s} = 0.01667 \text{ m}^3/\text{s}$$

$$V_1 = V_4 = \frac{4Q_1}{\pi D_1^2} = \frac{4 \cdot 0.01667 \text{ m}^3/\text{s}}{\pi \cdot 0.149 \text{ m}^2} = 0.9558 \text{ m/s}$$

$$V_3 = \frac{4Q_3}{\pi D_3^2} = \frac{4 \cdot 0.00833 \text{ m}^3/\text{s}}{\pi \cdot 0.047 \text{ m}^2} = 4.8 \text{ m/s}$$

$$Re_1 = \frac{V_1 D_1}{\nu} = \frac{0.9558 \text{ m/s} \cdot 0.149 \text{ m}}{1.3 \times 10^{-6} \text{ m}^2/\text{s}} = 109549 \quad 1.09 \times 10^5$$

$$\frac{D_1}{\epsilon} = \frac{0.149 \text{ m}}{1.5 \times 10^{-6} \text{ m}} = 99333 \quad f_1 \approx 0.0175$$

$$Re_3 = \frac{V_3 D_3}{\nu} = \frac{4.8 \text{ m/s} \cdot 0.047 \text{ m}}{1.3 \times 10^{-6} \text{ m}^2/\text{s}} = 173538 \quad 1.73 \times 10^5$$

$$\frac{D_3}{\epsilon} = \frac{0.047 \text{ m}}{1.5 \times 10^{-6} \text{ m}} = 31333 \quad f_3 \approx 0.0155$$

$$K_{red} \quad \frac{D_1}{D_2} \frac{0.149}{0.047} = 3.17$$

$$\theta = 30^\circ$$

$$K = 0.045$$

$$K_{enl}$$

$$\frac{D_2}{D_1} \frac{0.149}{0.047} = 3.17$$

$$\theta = 30^\circ$$

$$K = 0.48$$

$$\frac{\Delta P}{\gamma} = 0.0155 \cdot \frac{8 \cdot (0.00833 \text{ m}^3/\text{s})^2}{\pi^2 \cdot 0.047 \text{ m}^4 \cdot 9.81 \text{ m/s}^2} \left(\frac{30 \text{ m}}{0.047 \text{ m}} + 2 \cdot 30 \right) + \frac{8 \cdot (0.00833 \text{ m}^3/\text{s})^2}{\pi^2 \cdot 0.047 \text{ m}^4 \cdot 9.81 \text{ m/s}^2} (0.045 + 0.48) + 2 \cdot 0.0175 (60) \frac{8 \cdot (0.01667 \text{ m}^3/\text{s})^2}{\pi^2 \cdot 0.149 \text{ m}^4 \cdot 9.81 \text{ m/s}^2}$$

$$\frac{\Delta P}{\gamma} = 13.43$$

2.1

$$f = f_2 \frac{8Q_2^2}{\pi^2 D_2^4 g} \left(\frac{L_2}{D_2} + 2 \left(\frac{L_e}{D} \right)_{\text{entr}} \right) + \frac{8Q_2^2}{\pi^2 D_2^4 g} (K_{red} + K_{valve} + K_{ent}) + 2f_1 \left(\frac{L_e}{D} \right) + \frac{8Q_1^2}{\pi^2 D_1^4 g}$$

$$V_2 = \frac{4Q}{\pi D_2^2} = \frac{4 \cdot 0.00833}{\pi \cdot 0.093^2} = 1.226 \text{ m/s}$$

$$Re_1 = \frac{V_2 D_2}{\nu} = \frac{1.226 \cdot 0.093}{1.3 \times 10^{-6}} = 87,734 \approx 8.7 \times 10^4$$

$$\frac{D}{\epsilon} = \frac{0.093 \text{ m}}{1.5 \times 10^{-6}} = 62000 \quad f_2 \approx 0.018$$

$$K_{red} \quad D_1/D_2 = 0.149/0.093 = 1.6 \quad \theta = 30^\circ \quad 0.042$$

$$K_{ent} \quad D_2/D_1 = 0.149/0.093 = 1.6 \quad \theta = 30^\circ \quad 0.41$$

$$13.43 = 0.018 \cdot \frac{8 \cdot 0.00833^2}{\pi^2 \cdot 0.093^4 \cdot 9.81} \left(\frac{30 \text{ m}}{0.093 \text{ m}} + 2 \cdot 30 \right) + \frac{8 \cdot 0.00833^2}{\pi^2 \cdot 0.093^4 \cdot 9.81} (0.042 + K_{valve} + 0.41)$$

$$0.52$$

$$+ 2 \cdot 0.0179 \cdot 60 \frac{8 \cdot 0.01667^2}{\pi^2 \cdot 0.149^4 \cdot 9.81}$$

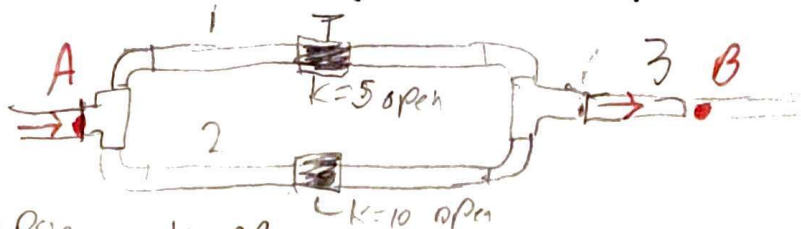
$$13.43 = 0.52 + 0.0766 (K_{valve} + 0.452) + 0.0977$$

$$12.8 = 0.0766 (K_{valve} + 0.452)$$

$$167 = K_{valve} + 0.452$$

$$K_{valve} = 166 \checkmark$$

6.



$$P_A = 20 \text{ Psig}$$

$$K = 0.9$$

elbow

Neglect tee and pipe losses

$$D_1 = 2 \text{ in Sch 40 Steel} = 0.1723 \text{ feet}$$

$$D_2 = 4 \text{ in Sch 40 Steel} = 0.3355 \text{ feet}$$

$$\frac{P_A}{\gamma} + \frac{V_A^2}{2g} + z_A = \frac{P_B}{\gamma} + \frac{V_B^2}{2g} + z_B + h_{LAB}$$

$$\frac{2015}{1 \text{ ft}^2} \cdot \frac{144 \text{ in}^2}{1 \text{ ft}^2}$$

$$\frac{P_A}{\gamma} = h_{LAB}$$

$$\frac{P_A}{\gamma} = h_{LAB1}$$

$$\frac{P_A}{\gamma} = h_{LAB2}$$

$$\frac{P_{A1}}{\gamma} = 2 \cdot K_{elbow} \frac{V_1^2}{2g} + K_{valve1} \frac{V_1^2}{2g}$$

$$\frac{P_{A2}}{\gamma} = 2 \cdot K_{elbow} \frac{V_2^2}{2g} + K_{valve2} \frac{V_2^2}{2g}$$

$$\frac{P_{A1}}{\gamma} = \frac{V_1^2}{2g} (2 \cdot K_{elbow} + K_{valve1})$$

$$\frac{P_{A1}}{\gamma} = \frac{16 Q_1^2}{\pi^2 D_1^4 \cdot 2g} (2 \cdot K_{elbow} + K_{valve1})$$

$$\frac{P_{A1}}{\gamma} = \frac{8 Q_1^2}{\pi^2 D_1^4 \cdot g} (2 \cdot K_{elbow} + K_{valve1})$$

$$\frac{P_{A1}}{\gamma} \cdot \frac{1}{2 \cdot K_{el} + K_{valve}} = \frac{8 Q_1^2}{\pi^2 D_1^4 \cdot g} \rightarrow \frac{P_{A1}}{\gamma} \cdot \frac{\pi^2 D_1^4 \cdot g}{2 \cdot K_{el} + K_{valve}} = 8 Q_1^2$$

$$Q_1 = \sqrt{\frac{1}{8} \frac{P_{A1}}{\gamma} \frac{\pi^2 D_1^4 \cdot g}{2 \cdot K_{elbow} + K_{valve1}}}$$

$$Q_2 = \sqrt{\frac{1}{8} \frac{P_{A2}}{\gamma} \frac{\pi^2 D_2^4 \cdot g}{2 \cdot K_{el} + K_{valve2}}}$$

$$Q_1 = \sqrt{\frac{1}{8} \cdot \frac{2880}{62.415} \cdot \frac{\pi^2 \cdot 0.1723^4 \cdot 32.2 \text{ ft/s}^2}{2(0.9) + 5}}$$

$$Q_2 = \sqrt{\frac{1}{8} \cdot \frac{2880}{62.415} \cdot \frac{\pi^2 \cdot 0.3355^4 \cdot 32.2 \text{ ft/s}^2}{2(0.9) + 10}}$$

$$Q_1 = 0.487 \text{ ft}^3/\text{s}$$

$$Q_2 = 1.40$$

$$Q_1 + Q_2 = Q_3$$

$$a. 0.487 + 1.40 \text{ ft}^3/\text{s}$$

$$Q_3 = 1.89 \text{ ft}^3/\text{s}$$

$$b. 0.40 \text{ ft}^3/\text{s}$$

$$c. 0.487 \text{ ft}^3/\text{s}$$