

Preston Hudlow

GEOG 419

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Lab 5

1: What part of the spectrum does bathymetric LiDAR such as the RIEGL sensor use, and how is Secchi disk depth only an approximation of how successful it can be used? What are the highest and lowest points in the digital bathymetric model (DBM) depth file (see layer job61232_003_002.tif)? (Hint: rt-click the layer and open its properties to find the statistics... Note: The vertical reference in our lab data is NAVD88 vertical datum in units of meters, which was requested in the download step using Digital Coast Data Access Viewer. <https://www.fisheries.noaa.gov/inport/item/60170>

Bathymetric LiDAR, like the RIEGL sensor, uses a green wavelength for better water penetration. Secchi disk depth approximates LiDAR effectiveness but is based on visual water clarity, while LiDAR also depends on laser power, angle, and water composition. The low values is -8.3 whereas the high is 6.7.

2: If it takes a strong laser light pulse to penetrate the water column and still yield a reflectance, why not just pump up the strength of the laser?

This could cause extra noise by using excessive energy which can produce multiple scattering. It also could affect the environment which could be unsafe to humans and marine life. nicely done

3: We know water refracts light, so how does this angular change in bathy lidar get corrected?

Refraction is corrected using Snell's Law, which adjusts for light's speed and direction change from air to water. LiDAR software applies correction algorithms to refine depth calculations.

4: What is the vertical positional accuracy of the LiDAR data? need to correct for refraction by having a measurement of the top of water and

LiDAR's vertical positional accuracy varies by sensor and conditions, typically ranging from ± 10 cm to ± 30 cm for bathymetric LiDAR.

5: Does bathymetric LiDAR work in the surf zone of a beach? Why/why not?

Bathymetric LiDAR struggles in the surf zone due to turbulence, bubbles, and high wave energy, which scatter laser pulses and hinder bottom detection.

6. What is the approximate swath width and post-spacing of the LiDAR in meters? 0-1m, 1-10m, 100+m Explain.

The pulses are range from 0-1m apart and can be due to the altitude at which the drone is sending the pulses. Lower altitude could result in ultra fine resolution and a higher amount of pulse returns.

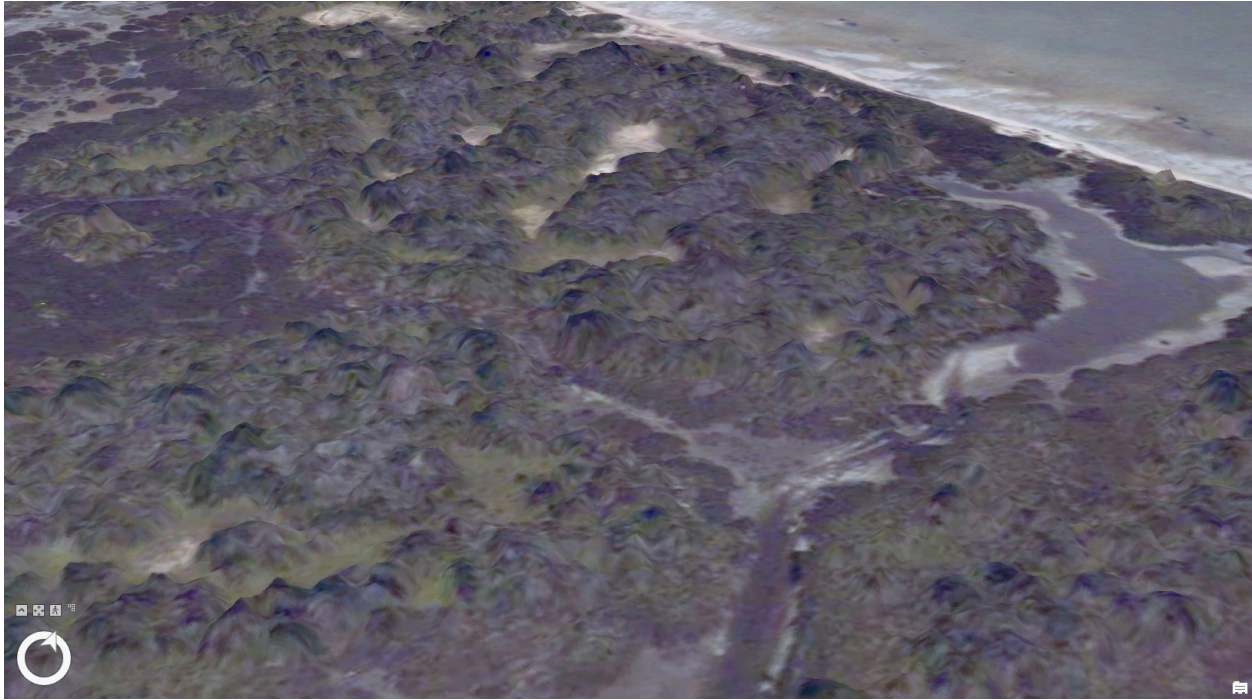
7. Visually examine the all-returns LiDAR points. Are any data voids evident? Explain possible causes of these (keep in mind the difference between the topo and bathy laser measurement systems and the surface features.)

Yes, you can see data voids in this due to areas with strong wave action or turbid water. This prevents laser penetration and can scatter the signals.

8. Inspect the bare surface areas of the remains of Diamond City. What can you infer or even measure about the building sites? Which layer is the DEM and which is the DSM? Were these areas potentially 7 elevated on dunes or berms? Include a screenshot to support your interpretation. Annotate if helpful.

One could infer that given the surfaces the building themselves were unstable and prone to disasters. The DEM would be the min layer showing the bare-earth whereas the DSM is the max layer showing the surfaces and elevation to the objects. I think these surfaces were elevated in dunes.





9-10: If Dr. Allen were to purchase his dream yacht, something like this 38ft Hunter 380 with a fixed 5ft (1.52m) keel, will he make it through the channel at the location above on a high tide OR will be grounded and forever marooned with the ghosts of Diamond City? Explain and include any supporting results. (You can also document your VDATUM calculation.)

$$7.352\text{m} - 1.52\text{m} = 5.832\text{m}$$

Safety margin

$$5.832 - 0.61 = 5.222\text{m}$$

Since the depth available is 5.222m Dr. Allen would have more than enough clearance and would safely pass through the channel at high tide.

Input

Latitude:

e.g. 33.7586 or 33 45 30.9600

Longitude:

e.g. -118.7691 or -118 46 8.7600

Height:

e.g. 3.037

to DMS

Vertical Uncertainty: 1 sigma 95% Confidence

Add Observation Vertical Uncertainty

Vertical_Area: NCinner11_8301:1:1

- Valid Tidal area
- Non-Tidal area
- Non-Valid area
- CRD
- IGLD85
- SVU area

Output

Latitude:

Longitude:

Height:

Vertical Uncertainty (+/-): 0.202 ft

